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1/77

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Your reference

Patent application number (The Patent Office will fill in this :

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Full name, address and postcode of the or of each applicant (underline all surnames)

Specialised Petroleum Services Group Limited Wellbore Completion Services

Arnhall Business Park Westhill

Patents ADP number (If you know it)

ABERDEEN AB32 6T0

If the applicant is a corporate body, give the country/state of its incorporation

United Kingdom

8460784001

4. Title of the invention

Improved Mechanism for Actuation of a Downhole Tool

(if you know it)

5. Name of your agent (If you have one)

"Address for service" in the United Kingdom to which all correspondence should be sent (including the postcode)

Kennedys Patent Agency Limited Queens House, Floor 5 29 St Vincent Place GLASGOW G1 2DT

Patents ADP number (if you know it)

08058240002

6. If you are declaring priority from one or more earlier patent applications, give the country and the date of filing of the or of each of these earlier applications and (If you know it) the or each application number

Country Priority application number

Date of filing (day / month / year)

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Date of filing (day / month / year)

8. Is a statement of inventorship and of right to grant of a patent required in support of this request? (Answer Yes' if:

a) any applicant named in part 3 is not an inventor, or

b) there is an inventor who is not named as an applicant, or.

 e) any named applicant is a corporate body. See note (d))

Yes

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Continuation sheets of this form ——
Description 18

Claim@ --

Drawing(s) 2

Abstract

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Priority documents

Translations of priority documents

Statement of inventorship and right to grant of a patent (Patents Form 7/77)

Request for preliminary examination and search (Patents Form 9/77)

Request for substantive examination (Pstents Form 10/77)

Any other documents (please specify)

I/We request the grant of a patent on the basis of this application.

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03.04.2003

 Name and daytime telephone number of person to contact in the United Kingdom

David Kennedy - 0141 226 6826

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Improved Mechanism for Actuation of a Downhole Tool

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The present invention relates to downhole tools as used in the oil and gas industry and in particular, though not exclusively, to a mechanism for moving a sleeve in a 5 downhole tool by passing a ball along a helical groove in б 7 the sleeve. 8 While many downhole tools operate continuously through a 9 well bore e.g. scrapers and brushes as disclosed in US 10 6,227,291, it is more desirable to provide a tool which 11 performs a function only when it has reached a preferred 12 . location within a well bore. An example of such a tool 13 would be a circulation tool as disclosed in WO 02/061236. 14 The tool provides a cleaning action on the walls of the 15 casing or lining of the well bore. The cleaning action is 16 only required after the casing has been brushed or 17 scraped and thus the tool is designed to be selectively 18 actuated in the well bore. Such tools provide the 19 advantage of allowing an operator to mount a number of 20

tools on a single work string and operate them

individually on a single trip in to the well bore. This

saves significant time in making the well operational.

Tools which are selectively actuable in a well bore 1 commonly operate by having an element which can be moved 2 relative to the tool when in the well bore. In the 3 circulation tool of WO 02/061236, the element is a sleeve 4 located in the cylindrical body of the tool. When run in 5 the well, the sleeve is held in a first position by one б 7 or more shear screws. To actuate the tool, a drop ball is released from the surface of the well through the work 8 string. On reaching the sleeve, the ball blocks the flow 9 of fluid through the tool and consequently pressure 10 builds up until the shear screws shear and the sleeve is 11 forced downwards. The movement of the sleeve is then 12 stopped when a lower ledge of the sleeve contacts a 13 shoulder on the internal surface of the tool body. 14 15 Such tools have a number of disadvantages. The tools are 16 generally limited to one actuable movement. If two 17 sleeves are incorporated to overcome this, the shear 18 screws of the second sleeve can operate prematurely under 19 the shock created to shear the shear screws of the first 20 sleeve. Additionally, the reduced bore diameter of the 21 lower part also effects the flow rate achievable through 22 23 the tool. One tool which has been developed to operate repeatedly

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25 is that disclosed in US 4,889,199. This tool comprises a 26 tubular body having a radial port into which is located a 27 sleeve having a matching radial port. The sleeve is 28 slidably mounted and its action controlled from a 29 deformable drop ball biasing the sleeve against a spring. 30 Initially the spring biases the sleeve to a closed 31 position in which the ports are misaligned. The drop ball 32 causes the sleeve to move to a position where the ports 33

1 align due to a build up of pressure behind the ball, and
2 fluid is discharged radially through the ports. A small
3 steel ball is then dropped into the tool which seals the

4 radial ports and the consequential pressure build up

5 extrudes the deformable ball through the ball seat. The

6 steel ball will drop with the deformable ball and both

7 are retained in a ball catcher at the base of the tool.

8 When the balls drop together the spring biases the sleeve

9 back to the closed position and the tool can be operated

10 repeatedly.

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A disadvantage of this tool is that it requires both a deformable ball and a smaller metal ball to operate. Care must then be taken to ensure the balls are dropped in the correct order. The smaller metal ball must lodge in the second, radial, outlet in order to stop flow and thus the tool is restricted to having a single radial port. This limits the amount of cleaning which can be performed. Yet

19 further is a disadvantage in that use of a rubber or

20 deformable ball is unreliable as the material can break

21 up or wear within the well bore.

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23 It is an object of the present invention to provide an 24 actuation mechanism for a downhole tool which obviates or 25 mitigates at least some of the disadvantages of the prior 26 art.

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It is a further object of at least one embodiment of the present invention to provide an actuation mechanism to move a sleeve within a downhole tool.

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32 It is a yet further object of at least one embodiment of 33 the present invention to provide an actuation mechanism 19 日本

for use in a downhole tool which is re-settable to allow 2 the tool to operate in a cyclic manner. 3 It is yet further object of at least one, embodiment of 4 the present invention to provide a circulation tool which 5 can be operated repeatedly using a single ball. 6 7 According to a first aspect of the present invention 8 there is provided an actuation mechanism for a downhole 9 tool, the mechanism comprising a substantially 10 cylindrical body having a central bore running axially 11 therethrough, a sleeve located within the bore, the 12 sleeve including a helical channel on an inner surface, 13 mechanical biasing means located between the sleeve and 14 the body to bias the sleeve in a first direction and a 15 ball, sized to run in the helical channel in a reverse 16 direction to prevent a majority of fluid flow through the 17 sleeve and cause the sleeve to move in the reverse 18 19 direction relative to the body. 20 When the ball is dropped in the body, fluid will drive 21 the ball into the channel and into the helical path. As 22 the ball is sized for the channel it will block the 23 majority of the fluid path through the tool and 24 consequently pressure will build up on the ball. This 25 pressure will be sufficient to move the ball and sleeve 26 together against the spring and force the sleeve in the 27 reverse direction. The movement of the sleeve actuates 28 the tool. On release of the ball from the channel the 29 sleeve is biased in the first direction back to its 30 31 original position.

1 Preferably the mechanical bias is a strong spring. The

2 spring may be helical, conical or the like. A strong
3 string will prevent the slave.

string will prevent the sleeve moving in the reverse

4 direction by fluid flow in the central bore.

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- 6 Preferably the helical channel has curved walls. This
- 7 will prevent damage to the ball. Preferably also the ball
- 8 is sized to provide a fluid by-pass around the ball when
- 9 in the channel. The ensures a positive pressure is
- 10 maintained behind the ball and prevents chattering of the
- 11 ball in the channel.

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- 13 The helical channel may be considered as a screw thread.
- 14 Thus the channel has a left hand thread so that the ball
- 15 travels in the opposite direction to the rotation of the
- 16 tool on a work string. Preferably a pitch of the thread
- 17 is greater than or equal to a diameter of the ball.

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- 19 Preferably the ball is spherical. More preferably the
- 20 ball is of a non-pliable material and thus cannot deform.
- 21 Advantageously the ball is made of steel.

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- 23 Preferably also the sleeve includes a conical surface at
- 24 an entrance to the channel. This funnels the ball into
- 25 the channel and ensures it travels into the helical path.

- 27 According to a second aspect of the present invention
- 28 there is provided a downhole tool for circulating fluid
- 29 in a borehole, the tool comprising a substantially
- 30 cylindrical body having a central bore running axially
- 31 therethrough, the body including at least one first port
- 32 arranged substantially transversely to the central bore,
- 33 a sleeve located within the bore, the sleeve including at

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least one second port arranged transversely to the central bore for discharging fluid from the central bore 2 when the first and second ports are aligned and 3 4 mechanical biasing means located between the sleeve and the body to bias the sleeve in a first direction at which 5 the ports are misaligned, wherein at least a portion of 6 the sleeve includes a helical channel on an inner surface 7 thereof, and the tool further includes at least one ball, 8 the ball being sized to run in the helical channel in a 9 reverse direction to prevent a majority of fluid flow 10 11 through the sleeve and cause the sleeve to move in the reverse direction relative to the body so that the ports 12 13 come into alignment. 14 Preferably the mechanical blas is a strong spring. The 15 spring may be helical, conical or the like. A strong 16 17 string will prevent the sleeve moving in the reverse 18 direction by fluid flow in the central bore. 19 Preferably the helical channel has curved walls. This 20 will prevent damage to the ball. Preferably also the ball 21 22 is sized to provide a fluid by-pass around the ball when in the channel. The ensures a positive pressure is 23 maintained behind the ball and prevents chattering of the 24

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ball in the channel.

27 The helical channel may be considered as a screw thread.

28 Thus the channel has a left hand thread so that the ball

29 travels in the opposite direction to the rotation of the

30 tool on a work string. Preferably a pitch of the thread

31 is greater than or equal to a diameter of the ball.

Preferably the ball is spherical. More preferably the

ball is of a non-pliable material and thus cannot deform.

Advantageously the ball is made of steel. 3

Preferably also the sleeve includes a conical surface at 5

an entrance to the channel. This funnels the ball into 6

the channel and ensures it travels into the helical path. 7

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- 9 Preferably the tool further comprises engagement means to
- control relative movement between the sleeve means and 10
- the body. Preferably also the mechanical bias biases the 11
- sleeve against the engagement means. 12

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- Preferably also the tool includes ball collecting means. 14
- The ball collecting means may be an element located in 15
- the casing means to prevent passage of the ball through 16
- the tool, but allowing passage of fluid through the tool. 17

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- Preferably said first and second ports are located 19 .
- substantially perpendicular to a longitudinal axis
- through the tool. More preferably there are a plurality 21
- of said first and said second ports. Advantageously there 22
- are three or more said first and said second outlets. 23
- Preferably also said first and said second outlets are 24
- spaced equidistantly around the body and the sleeve 25
- 26 respectively.

- Preferably said engagement means comprises at least one 28
- index pin located in a profiled groove. Preferably the at 29
- least one index pin is located on the body and the 30
- profiled groove is located on an outer surface of the 31
- sleeve. In this way, an index sleeve is produced with the 32
- groove determining the relative position of the sleeve to **33** .

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the body. Advantageously the groove extends 1 circumferentially around the sleeve, thus the tool can be 2 continuously cycled. 3 4 Preferably also the spring is located in a chamber 5 created between the sleeve and the body. Advantageously 6 the chamber includes an exhaust port such that fluid can .7 enter and be dispelled from the chamber by relative 8 movement of the sleeve and the body. 9 10 According to a third aspect of the present there is 11 provided a method of actuating a tool in a borehole, the 12 13 method comprising the steps; 14 inserting in a work string a tool including an 15 actuating mechanism according to the first aspect; 16 running the work string and tool into a borehole, 17 (b) 18 with the tool in a first operating position; 19 dropping a ball into the work string such that the ball travels along the helical channel and by virtue 20 of an increase in pressure on the ball, forcing the 21 sleeve to move and switching the tool to a second 22 23 operating position; and on exit of the ball from the channel, returning the 24 25 tool to the first operating position as the mechanical bias acts on the sleeve. 26

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According to a fourth aspect of the present invention there is provided a method of circulating fluid in a borehole, the method comprising the steps:

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inserting in a work string a tool including an I actuating mechanism according to the second aspect; 2 running the work string and tool into a borehole, 3 (b)

with the tool in a closed position wherein the ports 4

5 are misaligned and fluid flows through the central 6 bore;

dropping a ball into the work string such that the 7 (c) . 8 ball travels along the helical channel and by virtue of an increase in pressure on the ball, forcing the 9

sleeve to move and switching the tool to an open 10

·- position wherein the ports are aligned; 11

discharging fluid from the ports; and 12 (d)

on exit of the ball from the channel, returning the IЭ tool to the closed position as the mechanical bias 14 15 acts on the sleeve.

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Preferably the method further includes the steps of: 17

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(f) dropping a second ball, identical to the first ball, 19 into the work string such that the second ball 20

travels along the helical channel and by virtue of 21

22 an increase in pressure on the ball, forcing the

23 sleeve to move and switching the tool to an open 24

position wherein the ports are aligned; 25

discharging fluid from the ports; and 26

on exit of the ball from the channel, returning the 27 tool to the closed position as the mechanical bias 28 acts on the sleeve.

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With the sleeve and back in the first position, the steps 30 31

(f) to (h) can be repeated any number of times.

Preferably also the method includes the step of catching 1 the dropped balls in the work string. 2 3 According to a fifth aspect of the present invention 4 there is provided a method of circulating fluid in a 5 borehole, the method comprising the steps: 7 inserting in a work string a tool including an . 8 actuating mechanism according to the second aspect; 9 running the work string and tool into a borehole, 10 (b) with the tool in a first position wherein the ports 11 are misaligned and fluid flows through the work 12 13 string; dropping a ball into the work string such that the 14 ball travels along the helical channel and by virtue 15 of an increase in pressure on the ball, forcing the 16 sleeve to move into a second position relative to 17 the body wherein the ports are misaligned and fluid 18 19 flow is through the work string; on exit of the ball from the channel, moving the 20 (d) tool to a third position by wirtue of the mechanical 21 bias acting on the sleeve wherein the ports are 22 aligned and fluid flows through the ports. 23 24 Preferably the method further includes the steps of: 25 dropping a second ball, identical to the first ball, (e) into the work string such that the second ball travels along the helical channel and by virtue of an increase in pressure on the ball, forcing the sleeve to move the second position relative to the

casing wherein the first and second ports are

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misaligned and fluid flow is through the work 1 2 string; and on exit of the ball from the channel, moving the 3 (f) sleeve to the first position by virtue of the 4 mechanical wherein the first and second ports are 5 misaligned and fluid flows through the work string. 6 7 With the sleeve and casing back in the first position, 8 the steps (c) to (f) can be repeated any number of times. 10 Preferably also the method includes the step of catching 11 the dropped balls in the work string. 12 13 An embodiment of the present invention will now be described by way of example only with reference to the 15 following Figures, of which: 16 17 Figure 1 is a part cross-sectional view of a downhole 18 tool in a first position according to an embodiment of 19 20 the present invention; 21 Figure 2 is a part cross-sectional view of the downhole 22 tool of Figure 1 in a second position; 23 24 Figure 3 is a part cross-sectional view of the downhole 25 tool of Figure 1 in a third position; and Figures 4(a)-(c) are schematic illustrations of an index pin positioned in a groove of the tool of Figure 1 for the first, second and third positions respectively. 30 Reference is initially made to Figure 1 of the drawings which illustrates a downhole tool, generally indicated by

1 reference numeral 10, in accordance with an embodiment of

- 2 the present invention. Tool 10 includes a cylindrical
- 3 body 12 having an upper end 14, a lower end 16 and a
- 4 cylindrical bore 18 running therethrough. The body 12 has
- 5 a box section 20 located at the upper end 14 and a pin
- 6 section 22 located at the lower end 16 for connecting the
- 7 tool 10 in a work string or drill string (not shown).

8,

- 9 The body 12 further includes four radial ports 24 located
- 10 equidistantly around the body 12. The ports 24 are
- 11 perpendicular to the bore 18.

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- 13 Located on an inner surface 26 of the body 12 are two
- 14 opposing ledges 26, 28 used to limit axial movement of a
- 15 sleeve 30 located within the body 12. Sleeve 30 is sealed
- 16 against body 12 by o-rings 3la-d.

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- 18 Sleeve 30 is an annular body which also includes four
- 19 radial ports 32 located equidistantly around the sleeve
- 20 30. The ports 32 are perpendicular to the bore 18. The
- 21 ports 32 are of a similar size to the ports 24 in the
- 22 body 12.

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- 24 At an upper end 36 of the sleeve 30 is located a conical
- 25 surface 38 facing the upper end 14 of the tool 10.
- 26 Downwardly extending from the conical surface is a
- 27 helical channel 34. The channel 34 comprises a continuous
- 28 spiral groove, having curved walls 40, which takes the
- 29 path of a screw thread on the inner surface 39 of the
- 30 sleeve 30. The handedness of the 'screw thread' is left
- 31 handed.

1 Located between the outer surface 44 of the sleeve 30 and

- 2 the inner surface 46 of the body 12 is a space forming a
- 3 chamber 48. The upper edge of the chamber is formed from
- 4 a ledge 50 on the outer surface 44 of the sleeve 30. The
- 5 lower edge of the chamber 48 is formed from the ledge 28
- 6 of the body 12. A strong spring 52 is positioned within
- 7 the chamber 48 and compressed to bias against the ledge
- 8 50 of the sleeve 30. An exhaust port 54 is located
- 9 through the sleeve 30 at the chamber 48 to allow fluid
- 10 from the bore 42 to pass in to and out of the chamber 48
- 11 as the sleeve 30 is moved relative to the body 12.

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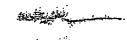
- 13 Further an engagement mechanism, generally indicated by
- 14 reference numeral 56, couples the sleeve 30 to the body
- 15 12 and controls relative movement there between.
- 16 Engagement mechanism 56 comprises an index sleeve 58,
- 17 being a portion of the sleeve 30, and a matching index
- 18 pin 60 located through the body 12 towards the sleeve 30.
- 19 Index sleeve 58 includes a profiled groove 62 on the
- 20 outer surface 44 of the sleeve 30 into which the index
- 21 pin 60 locates.

- 23 Reference is now made to Figure 4 of the drawings which
- 24 illustrates the groove 62 of the index sleeve 58. The
- 25 groove 62 extends circumferentially around the sleeve 30
- 26 in a continuous path. The groove 62 defines a path having
- 27 a substantially zig-zag profile to provided axial
  28 movement of the slower 20
- 28 movement of the sleeve 30 relative to the body 12.
- 29 Indeed, spring 52 biases the sleeve 30 against the index
- 30 pin 60. The path includes an extended longitudinal
- 31 portion 64 at every second upper apex of the zig-zag.
- 32 Further a stop 66 is located at the apexes of the zig-
- 33 zags to encourage the index pin 60 to remain at the

CONTRACTOR OF THE PARTY OF THE apexes and provide a locking function to the tool 10. The 1 stops 66 are in the direction of travel of the pin 60 2 3 along the groove 62. 4

Reference is now made to Figure 2 of the drawings which 5 illustrates the tool 10 of Figure 1, now with a ball 68 6 located in the bore 42. Like parts to those of Figure 1 7 have been given the same reference numeral for ease of 8 identification. Ball 68 is sized to travel along the 9 helical channel 34. Ideally the ball 68 is sized to have 10 a diameter less than or equal to the pitch of the screw 11 thread forming the walls 40 of the channel 34. In this 12 way when the ball 68 travels along the channel 34 a by-13 pass is created between the edge of the ball 68 and the walls 40 of the channel 34. The ball is of a hard 15 material which is non-pliable. Ideally the ball is made 16. 17 of a metal such as steel.

Reference is now made to Figure 3 of the drawings which 19 illustrates the tool 10 of Figure 1, now with the ball 68 20 exiting the sleeve 30 into the bore 18. Like parts to 21 those of Figures 1 and 2 have been given the same 22 reference numeral for ease of identification. Body 12 23 includes a pin 70 located into the bore 18. Pin 70 is a 24 ball retainer pin which blocks the passage of the ball 68 25 through the bore 18. Ball 68 will come to rest at the pin 26 70 and therefore be retrievable with the tool 10. Pin 70 27 does not prevent the flow of fluid through the bore 18 28 and from the tool 10 into the work string below. The pin 29 70 and the space 72 in the bore 18 immediately above it 30 may be considered as a ball catcher. 31



- 1 In use, tool 10 is connected to a work string using the
- 2 box section 20 and the pin section 22. As shown in
- 3 Figures 1 and 4(a), the spring 52 biases the sleeve 30
- 4 against the index pin 60 such that the pin 60 is located
- 5 in the base apex of the groove 62. This is referred to as
- 6 the first position of the tool 10. In this position,
- 7 sleeve ports 32 are located above body ports 24, thus
- 8 preventing fluid flow radially through these ports due to
- 9 their misalignment. All fluid flow is through bores 18,42
- 10 of the tool 10. The tool 10 is then run into a bore hole
- 11 until it reaches a location where cleaning of the bore
- 12 hole casing or circulation of the fluid through the tool
- 13 is required.

- 15 Drop ball 68 is then released through the bore of the
- 16 work string from a surface. Ball 68 travels by fluid
- 17 pressure to the conical surface 38 at the upper end 36 of
- 18 the sleeve 30. The ball 68 is funnelled into the helical
- 19 channel 34 where its progress is arrested. As the ball 68
- 20 is now blocking the majority of fluid flow through the
- 21 bore 42, fluid pressure will build up behind the ball and
- 22 force the ball along the helical channel 34. Due to the
- 23 size of the ball a small amount of fluid will be allowed
- 24 to by-pass the ball 68. This fluid by-pass ensures that a
- 25 positive pressure is maintained behind the ball 68 so
- 26 that the ball 68 does not flow towards the upper end 14
- 27 of the tool 10 also prevents the ball 68 from
- 28 'chattering' in the channel 34. As the ball 68 makes its
- 29 way along the channel 34 it acts as a temporary flow
- 30 restrictor allowing sufficient pressure to build up on
- 31 the ball 68 and sleeve 30 such that they can move in the
- 32 direction of applied pressure against the bias of the
- 33 spring. Consequently the sleeve 30 and ball 68 move to a

a traffic constant program for second position. This position is illustrated in Figure 2 1 and 4(b). Though the ball 68 at the top of the channel 34 2 it will be appreciated that this position can be reached 3 with the ball in this position or when the ball 68 has 4 travelled a distance down the channel 34. The spring 52 5 is compressed into a now smaller chamber 48. Fluid has 6 been expelled from the chamber 48 through the exhaust 7 port 54. The index pin 60 is now located at the top of 8 the longitudinal portion 64 of the groove 62. 9 Consequently the sleeve ports 32 have crossed the body 10 ports 24 and are now located below them. Fluid flow is 11 thus still entirely through the bores 18,42. 12 13 On reaching the base of the channel 34, at the sleeve 14 port 32, the ball 68 exits the channel 34 and free falls 15 from this point. The ball 68 travels by fluid pressure 16 until it is stopped by the pin 70 and is held in the 17 space 72. On release of the pressure, spring 52 moves the 18 sleeve 30 against the index pin 60 such that sleeve 19 travels to a third position. The third position is 20 illustrated in Figures 3 and 4(c). Fluid has been drawn 21 into the chamber 48 and this drawing and expelling of 22 fluid provides a hydraulic damping effect on the impact 23 on the pin 60. Index pin 60 is now located in an upper 24 apex of the groove 62 and the ports 24,32 are aligned. In 25 this third position fluid is expelled radially from the 26 tool 10 through the now aligned ports 24,32. The tool 10. 27 is locked in this position by virtue of the stop 66 on 28 the groove 62 which prevents movement of the sleeve 30 29 for small variations in fluid pressure. 30

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In order to close the ports 24,32, a second ball is 32 dropped from the surface through the work string. The 33

second ball, and indeed any ball subsequent to this, is · 1 identical to the first ball 68. The second ball will 2 travel to the conical surface 38. On the build up of 3 fluid pressure behind the ball 68 it travels along the 4 helical channel 34 and sleeve 30 will move downwards 5 against the bias of the spring 52. Consequently the index б pin 60 will be relocated into the next longitudinal 7 groove 64 of the groove 62 and thus the tool is returned 8 to the second position. When the second ball exits the 9 helical channel 34, the pin 60 and sleeve 30 will move 10 relatively back to the first position and the second ball 11 will come to rest by the first ball 68. Effectively the 12 tool is reset and by dropping further balls the tool 10 13 can be repeatedly cycled in an open and closed manner as often as desired. 15 16 It will be appreciated that although the description 17 refers to relative positions as being 'above' and 18. 'below', the tool of the present invention can equally 19 well be used in horizontal or inclined boreholes and is 20 not restricted to vertical boreholes. Additionally the 21 term 'borehole' can be used to refer to an open, cased or 22 23 lined well bore. 24 The principal advantage of the present invention is that 25 it provides an actuating mechanism which can be 26 repeatedly operated in a downhole tool. Further the 27 mechanism dispenses with the need for a ball seat having 28 a diameter smaller than the diameter of the drop ball and 29 thus the flow through area of a tool incorporating the 30 mechanism is improved over prior art drop ball actuated 31

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tools.

Further an embodiment of the invention advantageously 1 provides a downhole tool for circulating fluid in a 2 borehole which can be repeatedly operated by dropping 3 identical balls through the work string. A further 4 advantage is that the tool can have any number of radial 5 ports to increase the flow area if desired compared with б 7 the prior art. 8 Further as the actuating meachnism is located above the 9 ports, the ports are opened with no flow going across the 10 seals. This effectively saves the seals from excessive 11 wear. An additional advantage is in the ability of the 12 index sleeve to lock the circulating ports in position 13 when aligned. Yet further the entry and exit of fluid in 14 the chamber for the spring advantageously reduces the 15 impact on the index pin via the hydraulic damping effect. 16 17 Various modifications may be made to the invention herein 18 described without departing from the scope thereof. For 19 example, two or more index pins could be used to provide 20 increased stability to the tool and distribute the load on the pins. Additional radial ports could be located at longitudinal spacings on the tool to provide radial fluid flow across a larger area when the ports are open. The ports may have varying diameters which may provide a nozzle on the outer surface of the body to increase fluid

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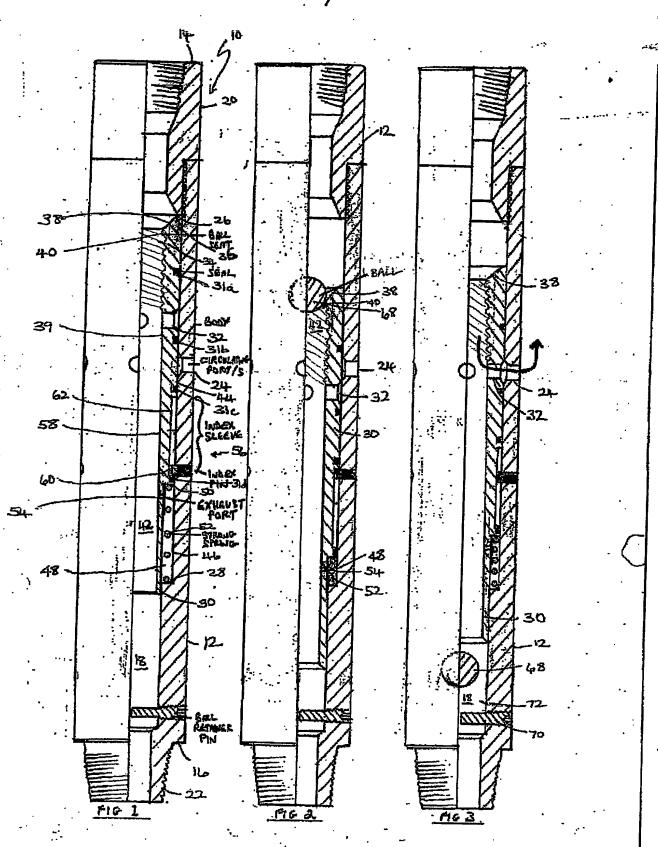
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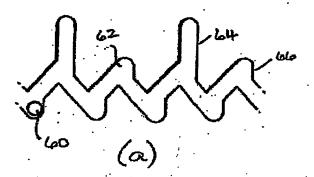
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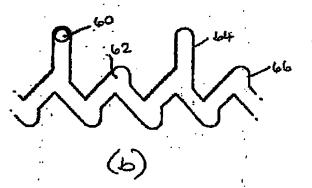
28

velocity.

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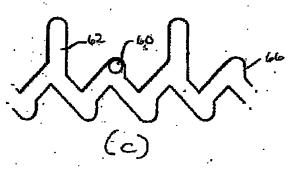


FIG 4

PCT/GB2004/001449